

### Example: Differentiation is ill-posed!

Let  $f : [0, 1] \rightarrow \mathbb{R}$  be continuously differentiable. Let  $f^\delta(x) = f(x) + n^\delta(x)$  with

$$n^\delta(x) = \sqrt{2}\delta\sin(2\pi kx)$$

for some  $k \in \mathbb{N}$ . Then

$$\begin{aligned} \int_0^1 |f^\delta(x) - f(x)|^2 dx &= 2\delta^2 \int_0^1 \sin^2(2\pi kx) dx, \\ &= \frac{\delta^2}{\pi k} \int_0^{2\pi k} \sin^2(z) dz, \\ &= \frac{\delta^2}{\pi k} \left( [-\cos(z)\sin(z)]_{z=0}^{2\pi k} + \int_0^{2\pi k} \cos^2(z) dz \right), \\ &= \frac{\delta^2}{\pi k} \int_0^{2\pi k} (1 - \sin^2(z)) dz. \end{aligned}$$

It follows  $2 \int_0^{2\pi k} (1 - \sin^2(z)) dz = 2\pi k$  such that

$$\int_0^1 |f^\delta(x) - f(x)|^2 dx = \delta^2.$$

Note that the frequency  $k$  of the noise can be arbitrarily large. We find

$$\partial_x f^\delta(x) = \partial_x f(x) + \sqrt{2}2\pi k\delta \cos(2\pi kx)$$

such that the squared  $L^2$  error

$$\begin{aligned} \int_0^1 |\partial_x f^\delta(x) - \partial_x f(x)|^2 dx &= 8\pi^2 k^2 \delta^2 \int_0^1 \cos^2(2\pi kx) dx \\ &= 4\pi^2 \delta^2 k^2, \end{aligned}$$

or the  $L^\infty$  error

$$\sup_{x \in [0,1]} |\partial_x f^\delta(x) - \partial_x f(x)| = \sqrt{2}2\pi\delta k.$$

can be arbitrarily large.

**Without regularization and without further information, the error between the exact and noisy solution can be arbitrarily large, even if the noise is arbitrarily small!**